

Deterministic Approximation for the Volume of the Truncated Fractional Matching Polytope

Heng Guo, **Vishvajeet N**

University of Edinburgh

ITCS 2025

Volume estimation

Given as **input convex body** in **high-dimensions**, estimate its **volume**

Volume estimation

Given as **input convex body** in **high-dimensions**, estimate its **volume**

- ▶ one of the most primitive tasks human beings have performed

Volume estimation

Given as **input convex body** in **high-dimensions**, estimate its **volume**

- ▶ one of the most primitive tasks human beings have performed
- ▶ fundamental parameter of any convex body

Volume estimation

Given as **input convex body** in **high-dimensions**, estimate its **volume**

- ▶ one of the most primitive tasks human beings have performed
- ▶ fundamental parameter of any convex body
- ▶ close connections to analysis and geometry, random walks, ...
[Kannan-Lovász-Simonovits95] [Bourgain86] [Dyer-Frieze-Kannan91], ...

Volume estimation

Given as **input convex body** in **high-dimensions**, estimate its **volume**

- ▶ one of the most primitive tasks human beings have performed
- ▶ fundamental parameter of any convex body
- ▶ close connections to analysis and geometry, random walks, ...
[Kannan-Lovász-Simonovits95] [Bourgain86] [Dyer-Frieze-Kannan91], ...
- ▶ exact computation is $\#P$ -hard!

Volume estimation

Given as **input convex body** in **high-dimensions**, estimate its **volume**

- ▶ one of the most primitive tasks human beings have performed
- ▶ fundamental parameter of any convex body
- ▶ close connections to analysis and geometry, random walks, ...
[Kannan-Lovász-Simonovits95] [Bourgain86] [Dyer-Frieze-Kannan91], ...
- ▶ exact computation is $\#P$ -hard!

We study **algorithms that approximately compute volume**

Approximate volume computation

Input: convex body K with volume V and $\epsilon > 0$

Approximate volume computation

Input: convex body K with volume V and $\epsilon > 0$

Output: approximate volume \tilde{V} s.t. $(1 - \epsilon)V \leq \tilde{V} \leq (1 + \epsilon)V$

Approximate volume computation

Input: convex body K with volume V and $\epsilon > 0$

Output: approximate volume \tilde{V} s.t. $(1 - \epsilon)V \leq \tilde{V} \leq (1 + \epsilon)V$

Time: $\text{poly}(\frac{1}{\epsilon}) \cdot \text{poly}(\#queries(K))$

Membership oracle model

Oracle \mathcal{O}_K : given point x , outputs whether $x \in K$ or a hyperplane separating x, K

Membership oracle model

Oracle \mathcal{O}_K : given point x , outputs whether $x \in K$ or a hyperplane separating x, K

► polynomial-time approximation algorithms

[Dyer-Frieze-Kannan91] ... [Jia-Laddha-Lee-Vempala24]

Membership oracle model

Oracle \mathcal{O}_K : given point x , outputs whether $x \in K$ or a hyperplane separating x, K

- ▶ polynomial-time approximation algorithms
[Dyer-Frieze-Kannan91] ... [Jia-Laddha-Lee-Vempala24]
- ▶ use counting-to-sampling reductions
[Jerrum-Valiant-Vazirani86]

Membership oracle model

Oracle \mathcal{O}_K : given point x , outputs whether $x \in K$ or a hyperplane separating x, K

- ▶ polynomial-time approximation algorithms
[Dyer-Frieze-Kannan91] ... [Jia-Laddha-Lee-Vempala24]
- ▶ use counting-to-sampling reductions
[Jerrum-Valiant-Vazirani86]
- ▶ work for general convex bodies

Membership oracle model

Oracle \mathcal{O}_K : given point x , outputs whether $x \in K$ or a hyperplane separating x, K

- ▶ polynomial-time approximation algorithms
[Dyer-Frieze-Kannan91] ... [Jia-Laddha-Lee-Vempala24]
- ▶ use counting-to-sampling reductions
[Jerrum-Valiant-Vazirani86]
- ▶ work for general convex bodies
- ▶ are fully polynomial-time randomized approximation schemes (FPRAS)

Quest for deterministic counting algorithms

correlation decay	#independent sets #matchings	[Weitz05] [Bayati-Gamarnik-Katz-Nair-Tetali07]
Barvinok's polynomial interpolation method	#independent sets # q -colorings	[Barvinok15] [Patel-Regts17] [Liu-Srivastava-Sinclair19] [Bencs-Berrekkaal-Regts24]
cluster expansion	#independent sets (dense random bipartite graphs)	[Helmuth-Perkins-Regts19] [Jensen-Keevash-Perkins20]
local CLTs	#independent sets #matchings	[Jain-Perkins-Sah-Sawhney21]
...

Quest for deterministic counting algorithms

correlation decay	#independent sets #matchings	[Weitz05] [Bayati-Gamarnik-Katz-Nair-Tetali07]
Barvinok's polynomial interpolation method	#independent sets # q -colorings	[Barvinok15] [Patel-Regts17] [Liu-Srivastava-Sinclair19] [Bencs-Berrekka-Regts24]
cluster expansion	#independent sets (dense random bipartite graphs)	[Helmuth-Perkins-Regts19] [Jensen-Keevash-Perkins20]
local CLTs	#independent sets #matchings	[Jain-Perkins-Sah-Sawhney21]
...

Can **deterministic** algorithms approximate volume?

Deterministic algorithms that approximate volume?

Unfortunately not for **general** convex bodies!

Deterministic algorithms that approximate volume?

Unfortunately not for **general** convex bodies!

- ▶ deterministic algorithms **require** exponential **#queries**
[Elekes86] [Bárány-Füredi87]

Deterministic algorithms that approximate volume?

Unfortunately not for **general** convex bodies!

- ▶ deterministic algorithms **require** exponential **#queries**
[Elekes86] [Bárány-Füredi87]

- ▶ hard instance : **adaptively-constructed** union of convex balls

Deterministic algorithms that approximate volume?

Unfortunately not for **general** convex bodies!

- ▶ deterministic algorithms **require** exponential **#queries**
[Elekes86] [Bárány-Füredi87]
- ▶ hard instance : **adaptively-constructed** union of convex balls

Do there exist poly-time **deterministic** algorithms for **nicely-representable** convex bodies?

Volume computation for general polytopes

Input: convex region defined by $Ax \leq b$ for $A \in \mathbb{R}^n \times \mathbb{R}^n, x, b \in \mathbb{R}^n$

Volume computation for general polytopes

Input: convex region defined by $Ax \leq b$ for $A \in \mathbb{R}^n \times \mathbb{R}^n, x, b \in \mathbb{R}^n$

- ▶ trivial membership oracle exists, thus:
- ▶ ignore structure, use randomized algorithm [Jia-Laddha-Lee-Vempala24]

Volume computation for general polytopes

Input: convex region defined by $Ax \leq b$ for $A \in \mathbb{R}^n \times \mathbb{R}^n, x, b \in \mathbb{R}^n$

- ▶ trivial membership oracle exists, thus:
- ▶ ignore structure, use randomized algorithm [Jia-Laddha-Lee-Vempala24]

Deterministic algorithms for general polytopes?

Volume computation for general polytopes

Input: convex region defined by $Ax \leq b$ for $A \in \mathbb{R}^n \times \mathbb{R}^n, x, b \in \mathbb{R}^n$

- ▶ trivial membership oracle exists, thus:
- ▶ ignore structure, use randomized algorithm [Jia-Laddha-Lee-Vempala24]

Deterministic algorithms for general polytopes?

- ▶ *all known* deterministic algorithms for general polytopes work in exponential time! [Barvinok93] [Lawrence91]

Volume computation for general polytopes

Input: convex region defined by $Ax \leq b$ for $A \in \mathbb{R}^n \times \mathbb{R}^n, x, b \in \mathbb{R}^n$

- ▶ trivial membership oracle exists, thus:
- ▶ ignore structure, use randomized algorithm [Jia-Laddha-Lee-Vempala24]

Deterministic algorithms for general polytopes?

- ▶ *all known* deterministic algorithms for general polytopes work in exponential time! [Barvinok93] [Lawrence91]
- ▶ are exact algorithms, achieve exponentially-small error!

Polytopes with underlying combinatorial structure

Input: convex region defined by combinatorial polytope $Ax \leq b$
for $A \in \mathbb{R}^n \times \mathbb{R}^n, x, b \in \mathbb{R}^n$

Polytopes with underlying combinatorial structure

Input: convex region defined by **combinatorial polytope** $Ax \leq b$
for $A \in \mathbb{R}^n \times \mathbb{R}^n, x, b \in \mathbb{R}^n$

e.g. independent set, matching polytope, hypergraph matching polytope, ...

Polytopes with underlying combinatorial structure

Input: convex region defined by **combinatorial polytope** $Ax \leq b$
for $A \in \mathbb{R}^m \times \mathbb{R}^n, x, b \in \mathbb{R}^n$

e.g. independent set, matching polytope, hypergraph matching polytope, ...

Can we **leverage combinatorial structure** of input polytope to **deterministically approximate volume** in **polynomial-time**?

Prior work: fractional independent set polytope

Definition (fractional independent set polytope)

Given graph $G = (V, E)$, the *fractional independent set polytope* is defined as

$$I_G := \{ \mathbf{x} \in [0, 1]^V \mid x_u + x_v \leq 1 \text{ for every } uv \in E \}$$

Prior work: fractional independent set polytope

Definition (fractional independent set polytope)

Given graph $G = (V, E)$, the *fractional independent set polytope* is defined as

$$I_G := \{ \mathbf{x} \in [0, 1]^V \mid x_u + x_v \leq 1 \text{ for every } uv \in E \}$$

Restrict every variable to $[0, \frac{1}{2} + \delta]$:

Prior work: fractional independent set polytope

Definition (fractional independent set polytope)

Given graph $G = (V, E)$, the *fractional independent set polytope* is defined as

$$I_G := \left\{ \mathbf{x} \in [0, 1]^V \mid x_u + x_v \leq 1 \text{ for every } uv \in E \right\}$$

Restrict every variable to $\left[0, \frac{1}{2} + \delta\right]$:

Definition (truncated fractional independent set polytope)

Given graph $G = (V, E)$, the *truncated fractional independent set polytope* is defined as

$$I_{G,\delta} := \left\{ \mathbf{x} \in \left[0, \frac{1}{2} + \delta\right]^V \mid x_u + x_v \leq 1 \text{ for every } uv \in E \right\}$$

Prior work: algorithms for $\text{Vol}(I_{G,\delta})$

Definition (truncated fractional independent set polytope)

$$I_{G,\delta} := \left\{ \mathbf{x} \in \left[0, \frac{1}{2} + \delta \right]^V \mid x_u + x_v \leq 1 \text{ for every } uv \in E \right\}$$

- ▶ [Gamarnik-Smedira23] gave deterministic quasi-polynomial time algorithm

truncation interval : $\left[0, \frac{1}{2} + \frac{O(1)}{\Delta^2} \right]$

Prior work: algorithms for $\text{Vol}(I_{G,\delta})$

Definition (truncated fractional independent set polytope)

$$I_{G,\delta} := \left\{ \mathbf{x} \in \left[0, \frac{1}{2} + \delta \right]^V \mid x_u + x_v \leq 1 \text{ for every } uv \in E \right\}$$

- ▶ [Gamarnik-Smedira23] gave deterministic quasi-polynomial time algorithm

truncation interval : $\left[0, \frac{1}{2} + \frac{O(1)}{\Delta^2} \right]$

- ▶ technique: correlation decay

Prior work: algorithms for $\text{Vol}(I_{G,\delta})$

Definition (truncated fractional independent set polytope)

$$I_{G,\delta} := \left\{ \mathbf{x} \in \left[0, \frac{1}{2} + \delta \right]^V \mid x_u + x_v \leq 1 \text{ for every } uv \in E \right\}$$

- ▶ [Gamarnik-Smedira23] gave deterministic quasi-polynomial time algorithm

truncation interval : $\left[0, \frac{1}{2} + \frac{O(1)}{\Delta^2} \right]$

- ▶ technique: correlation decay

- ▶ [Bencs-Regts24] gave FPTAS

truncation interval : $\left[0, \frac{1}{2} + \frac{O(1)}{\Delta} \right]$

Prior work: algorithms for $\text{Vol}(I_{G,\delta})$

Definition (truncated fractional independent set polytope)

$$I_{G,\delta} := \left\{ \mathbf{x} \in \left[0, \frac{1}{2} + \delta \right]^V \mid x_u + x_v \leq 1 \text{ for every } uv \in E \right\}$$

- ▶ [Gamarnik-Smedira23] gave deterministic quasi-polynomial time algorithm

$$\text{truncation interval : } \left[0, \frac{1}{2} + \frac{O(1)}{\Delta^2} \right]$$

- ▶ technique: correlation decay

- ▶ [Bencs-Regts24] gave FPTAS

$$\text{truncation interval : } \left[0, \frac{1}{2} + \frac{O(1)}{\Delta} \right]$$

- ▶ technique: Barvinok's polynomial interpolation method

Our work: Fractional Matching Polytope

We consider natural dual of independent set polytope

Our work: Fractional Matching Polytope

We consider natural **dual of independent set polytope**

Definition (fractional matching polytope)

Given graph $G = (V, E)$, the *fractional matching polytope* is defined as

$$P_G := \left\{ \mathbf{x} \in [0, 1]^E \mid \sum_{e \sim v} x_e \leq 1 \text{ for every } v \in V \right\}$$

where $e \sim v$ if the edge e is adjacent to v

Our work: Fractional Matching Polytope

We consider natural **dual of independent set polytope**

Definition (fractional matching polytope)

Given graph $G = (V, E)$, the *fractional matching polytope* is defined as

$$P_G := \left\{ \mathbf{x} \in [0, 1]^E \mid \sum_{e \sim v} x_e \leq 1 \text{ for every } v \in V \right\}$$

where $e \sim v$ if the edge e is adjacent to v

- note: volume of polytope and dual can be quite different

Truncated fractional matching polytope

- ▶ restrict each variable to interval $M_\delta = [0, \frac{1+\delta}{\Delta}]$, then $P_{G,\delta} = M_\delta^E \cap P_G$:

Definition (truncated fractional matching polytope)

For $\delta > 0$ and a graph $G = (V, E)$ of maximum degree Δ , the *truncated fractional matching polytope* is defined as follows

$$P_{G,\delta} := \left\{ \mathbf{x} \in \left[0, \frac{1+\delta}{\Delta}\right]^E \mid \sum_{e \sim v} x_e \leq 1 \text{ for every } v \in V \right\}$$

Truncated fractional matching polytope

- ▶ restrict each variable to interval $M_\delta = [0, \frac{1+\delta}{\Delta}]$, then $P_{G,\delta} = M_\delta^E \cap P_G$:

Definition (truncated fractional matching polytope)

For $\delta > 0$ and a graph $G = (V, E)$ of maximum degree Δ , the *truncated fractional matching polytope* is defined as follows

$$P_{G,\delta} := \left\{ \mathbf{x} \in \left[0, \frac{1+\delta}{\Delta}\right]^E \mid \sum_{e \sim v} x_e \leq 1 \text{ for every } v \in V \right\}$$

- ▶ multiplicative relaxation of trivial truncation interval $[0, \frac{1}{\Delta}]$
($P_{G,0} \equiv |E|$ -dimensional cube)

Truncated fractional matching polytope

- ▶ restrict each variable to interval $M_\delta = [0, \frac{1+\delta}{\Delta}]$, then $P_{G,\delta} = M_\delta^E \cap P_G$:

Definition (truncated fractional matching polytope)

For $\delta > 0$ and a graph $G = (V, E)$ of maximum degree Δ , the *truncated fractional matching polytope* is defined as follows

$$P_{G,\delta} := \left\{ \mathbf{x} \in \left[0, \frac{1+\delta}{\Delta}\right]^E \mid \sum_{e \sim v} x_e \leq 1 \text{ for every } v \in V \right\}$$

- ▶ multiplicative relaxation of trivial truncation interval $[0, \frac{1}{\Delta}]$ ($P_{G,0} \equiv |E|$ -dimensional cube)
- ▶ let C_v is satisfied $\Leftrightarrow \sum_{e \sim v} x_e \leq 1$

$$\text{Observe } \text{Vol}(P_{G,\delta}) := \int_{M_\delta^E} \prod_{v \in V} \mathbb{1}_{C_v} d\mu$$

Our main theorem for graph polytope volume

Theorem (truncated fractional matching polytope)

For any graph G of maximum degree $\Delta \geq 2$ and $\delta \leq \frac{C}{\Delta}$ for some constant $C > 0$, there is a fully polynomial-time approximation scheme (FPTAS) for $\text{Vol}(P_{G,\delta})$

Our main theorem for graph polytope volume

Theorem (truncated fractional matching polytope)

For any graph G of maximum degree $\Delta \geq 2$ and $\delta \leq \frac{C}{\Delta}$ for some constant $C > 0$, there is a fully polynomial-time approximation scheme (FPTAS) for $\text{Vol}(P_{G,\delta})$

- ▶ using [Bencs-Regts24] directly yields $\delta \leq \frac{C}{\Delta^2}$

Our main theorem for graph polytope volume

Theorem (truncated fractional matching polytope)

For any graph G of maximum degree $\Delta \geq 2$ and $\delta \leq \frac{C}{\Delta}$ for some constant $C > 0$, there is a fully polynomial-time approximation scheme (FPTAS) for $\text{Vol}(P_{G,\delta})$

▶ using [Bencs-Regts24] directly yields $\delta \leq \frac{C}{\Delta^2}$

▶ technique we use: cluster expansion

Polymer models

- ▶ Finite ground set \mathcal{P} whose elements are called *polymers*

Polymer models

- ▶ Finite ground set \mathcal{P} whose elements are called *polymers*
- ▶ \mathcal{P} endowed with a *symmetric and reflexive relation* $\not\sim$ that assigns *incompatibility* between any two polymers

Polymer models

- ▶ Finite ground set \mathcal{P} whose elements are called *polymers*
- ▶ \mathcal{P} endowed with a *symmetric and reflexive relation* $\not\sim$ that assigns *incompatibility* between any two polymers
- ▶ $w(\cdot)$ assigns *weight* $w(\gamma)$ to polymer γ

Polymer models

- ▶ Finite ground set \mathcal{P} whose elements are called *polymers*
- ▶ \mathcal{P} endowed with a *symmetric and reflexive relation* $\not\sim$ that assigns *incompatibility* between any two polymers
- ▶ $w(\cdot)$ assigns *weight* $w(\gamma)$ to polymer γ

Definition (polymer model partition function)

$$\Xi(\mathcal{P}, w) := \sum_{\Gamma} \prod_{\gamma \in \Gamma} w(\gamma),$$

where the sum is over compatible $\Gamma \subseteq \mathcal{P}$

Cluster expansion

Definition (cluster expansion)

cluster expansion of Ξ is the infinite power series:

$$\log \Xi(\mathcal{P}, w) := \sum_{\Gamma \in \mathcal{C}} \Phi(\Gamma) \prod_{\gamma \in \Gamma} w(\gamma)$$

where \mathcal{C} is the set of “clusters”

recall $\Xi(\mathcal{P}, w) := \sum_{\Gamma} \prod_{\gamma \in \Gamma} w(\gamma)$

Convergence of cluster expansion

Proposition (Kotecký-Preiss criterion [KP86])

Let $g : \mathcal{P} \rightarrow [0, \infty)$ be a “decay function”. Suppose that for all $\gamma \in \mathcal{P}$, we have,

$$\sum_{\gamma' \neq \gamma} |w(\gamma')| e^{|\gamma'| + g(\gamma')} \leq |\gamma|$$

Then, the *cluster expansion converges absolutely*

Algorithms from cluster expansion convergence

Proposition ([Jenssen-Keevash-Perkins20])

Fix an integer $\Delta > 0$ and let \mathcal{G} be a class of graphs of maximum degree at most Δ . Suppose the following conditions hold for a given polymer model with decay function $g(\cdot)$:

- (1) there exists $\rho > 0$ such that for every $G \in \mathcal{G}$ and every polymer $\gamma \in \mathcal{P}(G)$, $g(\gamma) \geq \rho|\gamma|$
- (2) there exist constants $c_1, c_2 > 0$ such that given a connected subgraph γ , determining whether γ is a polymer, and then computing $w(\gamma)$ and $g(\gamma)$ can be done in time $O(|\gamma|^{c_1} e^{c_2|\gamma|})$
- (3) the Kotecký-Preiss criterion is satisfied

Then there exists an FPTAS for $\Xi(G)$ for every $G \in \mathcal{G}$

Algorithms from cluster expansion convergence

Proposition ([Jenssen-Keevash-Perkins20])

Fix an integer $\Delta > 0$ and let \mathcal{G} be a class of graphs of maximum degree at most Δ . Suppose the following conditions hold for a given polymer model with decay function $g(\cdot)$:

- (1) there exists $\rho > 0$ such that for every $G \in \mathcal{G}$ and every polymer $\gamma \in \mathcal{P}(G)$, $g(\gamma) \geq \rho|\gamma|$
- (2) there exist constants $c_1, c_2 > 0$ such that given a connected subgraph γ , determining whether γ is a polymer, and then computing $w(\gamma)$ and $g(\gamma)$ can be done in time $O(|\gamma|^{c_1} e^{c_2|\gamma|})$
- (3) the Kotecký-Preiss criterion is satisfied

Then there exists an FPTAS for $\Xi(G)$ for every $G \in \mathcal{G}$

► [Jenssen-Keevash-Perkins20] proof uses Barvinok's interpolation method

Key insight: volume is polymer model partition function

$$\begin{aligned}\text{Vol}(P_{G,\delta}) &= \int_{M_\delta^E} \prod_{v \in V} \mathbb{1}_{C_v} d\mu \\ &= \dots \\ &= \left(\frac{1+\delta}{\Delta}\right)^{|E|} \sum_{S \subseteq V} \prod_{K \in \mathcal{K}(S)} w(K)\end{aligned}$$

Key insight: volume is polymer model partition function

$$\begin{aligned}\text{Vol}(P_{G,\delta}) &= \int_{M_\delta^E} \prod_{v \in V} \mathbb{1}_{C_v} d\mu \\ &= \dots \\ &= \left(\frac{1+\delta}{\Delta}\right)^{|E|} \sum_{S \subseteq V} \prod_{K \in \mathcal{K}(S)} w(K)\end{aligned}$$

- ▶ $S \subseteq [V]$ is a polymer if induced subgraph $G[S]$ is connected

Key insight: volume is polymer model partition function

$$\begin{aligned}\text{Vol}(P_{G,\delta}) &= \int_{M_\delta^E} \prod_{v \in V} \mathbb{1}_{C_v} d\mu \\ &= \dots \\ &= \left(\frac{1+\delta}{\Delta}\right)^{|E|} \sum_{S \subseteq V} \prod_{K \in \mathcal{K}(S)} w(K)\end{aligned}$$

- ▶ $S \subseteq [V]$ is a polymer if induced subgraph $G[S]$ is connected
- ▶ $S_1 \not\sim S_2$ if $\text{dist}_G(S_1, S_2) \leq 1$

Key insight: volume is polymer model partition function

$$\begin{aligned}\text{Vol}(P_{G,\delta}) &= \int_{M_\delta^E} \prod_{v \in V} \mathbb{1}_{C_v} d\mu \\ &= \dots \\ &= \left(\frac{1+\delta}{\Delta}\right)^{|E|} \sum_{S \subseteq V} \prod_{K \in \mathcal{K}(S)} w(K)\end{aligned}$$

- ▶ $S \subseteq [V]$ is a polymer if induced subgraph $G[S]$ is connected
- ▶ $S_1 \not\sim S_2$ if $\text{dist}_G(S_1, S_2) \leq 1$
- ▶ $w(S) = (-1)^{|S|} \int_{M_\delta^{E(S)}} \prod_{v \in S} \mathbb{1}_{\overline{C_v}} d\mu$

Proof sketch

- ▶ each polymer S encodes a connected component $G[S]$ of violated constraints

Proof sketch

- ▶ each polymer S encodes a connected component $G[S]$ of violated constraints
- ▶ Kotecký-Preiss: weight of the polymers decay rapidly with size \implies logarithm of partition function converges

Proof sketch

- ▶ each polymer S encodes a connected component $G[S]$ of violated constraints
- ▶ Kotecký-Preiss: weight of the polymers decay rapidly with size \implies logarithm of partition function converges
- ▶ [Jenssen-Keevash-Perkins20] algorithm: convergence implies using Barvinok's interpolation method we can truncate the partition function up to logarithmically-many terms for a good approximation

Proof sketch

- ▶ each polymer S encodes a connected component $G[S]$ of violated constraints
- ▶ Kotecký-Preiss: weight of the polymers decay rapidly with size \implies logarithm of partition function converges
- ▶ [Jenssen-Keevash-Perkins20] algorithm: convergence implies using Barvinok's interpolation method we can truncate the partition function up to logarithmically-many terms for a good approximation
- ▶ [Jenssen-Keevash-Perkins20] also requires weights of some polymers can be computed efficiently; but those conditions are easy to verify

Verifying Kotecký-Preiss criterion

$$|w(S)| = \int_{M_\delta^{E(S)}} \prod_{v \in S} \mathbb{1}_{\overline{C}_v} d\mu$$

- ▶ view polymer weight as joint probability of constraints being violated

Verifying Kotecký-Preiss criterion

$$|w(S)| = \int_{M_\delta^{E(S)}} \prod_{v \in S} \mathbb{1}_{\overline{C_v}} d\mu$$

- ▶ view polymer weight as joint probability of constraints being violated
- ▶ pick maximal independent set on the vertices, so sets of constraints are independent

$$|w(S)| = \Pr \left[\bigwedge_{v \in S} \overline{C_v} \right] \leq \Pr \left[\bigwedge_{v \in I_S} \overline{C_v} \right] = \prod_{v \in I_S} \Pr [\overline{C_v}]$$

Verifying Kotecký-Preiss criterion

$$|w(S)| = \int_{M_\delta^{E(S)}} \prod_{v \in S} \mathbb{1}_{\overline{C}_v} d\mu$$

- ▶ view polymer weight as joint probability of constraints being violated
- ▶ pick maximal independent set on the vertices, so sets of constraints are independent

$$|w(S)| = \Pr \left[\bigwedge_{v \in S} \overline{C}_v \right] \leq \Pr \left[\bigwedge_{v \in I_S} \overline{C}_v \right] = \prod_{v \in I_S} \Pr [\overline{C}_v]$$

- ▶ small truncation interval implies probability of violation of a set of constraints decays exponentially in its size

Our main theorem for graph polytope volume

Theorem (truncated fractional matching polytope)

For any graph G of maximum degree $\Delta \geq 2$ and $\delta \leq \frac{C}{\Delta}$ for some constant $C > 0$, there is a fully polynomial-time approximation scheme (FPTAS) for $\text{Vol}(P_{G,\delta})$

Hypergraph matching polytope

H with maximum degree Δ and maximum hyperedge size k

Hypergraph matching polytope

H with maximum degree Δ and maximum hyperedge size k

► using similar polymer model as before:

$$\text{Vol}(P_{H,\delta}) = \sum_{S \subseteq V} \int_{M_\delta^{E \setminus E(S)}} 1 d\mu \left(\prod_{K \in \mathcal{K}(S)} (-1)^{|K|} \int_{M_\delta^{E(K)}} \prod_{v \in K} \mathbb{1}_{\overline{C}_v} d\mu \right)$$

Hypergraph matching polytope

H with maximum degree Δ and maximum hyperedge size k

► using similar polymer model as before:

$$\text{Vol}(P_{H,\delta}) = \sum_{S \subseteq V} \int_{M_\delta^{E \setminus E(S)}} 1 d\mu \left(\prod_{K \in \mathcal{K}(S)} (-1)^{|K|} \int_{M_\delta^{E(K)}} \prod_{v \in K} \mathbb{1}_{\overline{C}_v} d\mu \right)$$

Theorem ((weaker) fractional hypergraph matching polytope)

For hypergraphs of maximum degree $\Delta \geq 2$ and maximum hyperedge size k and truncation parameter $\delta \leq \Theta\left(\frac{1}{\Delta k}\right)^{k-1}$, there is a fully polynomial-time approximation scheme (FPTAS) for $\text{Vol}(P_{H,\delta})$

Hypergraph matching polytope

Theorem (fractional hypergraph matching polytope)

For hypergraphs of maximum degree $\Delta \geq 2$ and maximum hyperedge size $k \geq 2$, and $\delta \leq \frac{C}{\Delta^{\frac{2k-3}{k-1}} k}$ for some constant $C > 0$, there is an FPTAS for $\text{Vol}(P_{H,\delta})$

- ▶ improvement over truncation parameter $\delta \leq \Theta\left(\frac{1}{\Delta k}\right)^{k-1}$

Hypergraph matching polytope

Theorem (fractional hypergraph matching polytope)

For hypergraphs of maximum degree $\Delta \geq 2$ and maximum hyperedge size $k \geq 2$, and $\delta \leq \frac{C}{\Delta^{\frac{2k-3}{k-1}} k}$ for some constant $C > 0$, there is an FPTAS for $\text{Vol}(P_{H,\delta})$

- ▶ improvement over truncation parameter $\delta \leq \Theta\left(\frac{1}{\Delta k}\right)^{k-1}$
- ▶ carefully working with hypergraph structure and constructing polymers which are *minimal connected subgraphs* (MCSes) in the incidence graph of H

Hypergraph matching polytope

Theorem (fractional hypergraph matching polytope)

For hypergraphs of maximum degree $\Delta \geq 2$ and maximum hyperedge size $k \geq 2$, and $\delta \leq \frac{C}{\Delta^{\frac{2k-3}{k-1}} k}$ for some constant $C > 0$, there is an FPTAS for $\text{Vol}(P_{H,\delta})$

- ▶ improvement over truncation parameter $\delta \leq \Theta\left(\frac{1}{\Delta k}\right)^{k-1}$
- ▶ carefully working with hypergraph structure and constructing polymers which are *minimal connected subgraphs* (MCSes) in the incidence graph of H
- ▶ crucially uses a combination of our technique with that of [Bencs-Regts24]

Hypergraph matching polytope

Theorem (fractional hypergraph matching polytope)

For hypergraphs of maximum degree $\Delta \geq 2$ and maximum hyperedge size $k \geq 2$, and $\delta \leq \frac{C}{\Delta^{\frac{2k-3}{k-1}} k}$ for some constant $C > 0$, there is an FPTAS for $\text{Vol}(P_{H,\delta})$

- ▶ improvement over truncation parameter $\delta \leq \Theta\left(\frac{1}{\Delta k}\right)^{k-1}$
- ▶ carefully working with hypergraph structure and constructing polymers which are *minimal connected subgraphs* (MCSes) in the incidence graph of H
- ▶ crucially uses a combination of our technique with that of [Bencs-Regts24]
- ▶ Kotecký-Preiss criterion analysis requires a **hypergraph generalization of broken circuit theory for graphs** [Whitney32] [Tutte54]

Summary

- We studied **deterministic volume approximation** for the **truncation** of the **fractional matching polytope**, which is the natural dual of the independent set polytope

Summary

- We studied **deterministic volume approximation** for the **truncation** of the **fractional matching polytope**, which is the natural dual of the independent set polytope
- We obtain an **FPTAS** for **polytope volume** using the **cluster expansion** technique

Summary

- We studied **deterministic volume approximation** for the **truncation** of the **fractional matching polytope**, which is the natural dual of the independent set polytope
- We obtain an **FPTAS** for **polytope volume** using the **cluster expansion** technique
- We develop an **FPTAS** for the truncation of the **hypergraph matching polytope**, analyzed using a **novel generalization of broken circuit theory for hypergraphs**

Future directions

- Faster FPTAS?

$f(\Delta)n^c$ running time instead of current $n^{f(\Delta)}$?

Future directions

- Faster FPTAS?

$f(\Delta)n^c$ running time instead of current $n^{f(\Delta)}$?

- Expanding truncation interval?

larger than $[0, \frac{c}{\Delta}]$ and as big as $[0, 1 - \epsilon)$?

Future directions

- Faster FPTAS?

$f(\Delta)n^c$ running time instead of current $n^{f(\Delta)}$?

- Expanding truncation interval?

larger than $[0, \frac{c}{\Delta}]$ and as big as $[0, 1 - \epsilon]$?

- Relaxing constant-degree assumption?

perhaps on special classes of graphs like expander, random, bipartite graphs?

Thank you!